

• Lecture 9: Central forces

$$\vec{F} = f(r) \hat{r}$$

- One of the most fascinating topics in classical physics.
- We will apply Newtonian physics to the general problem of central force motion.
- First $\rightarrow$ general feature of a system of two particles interacting with a central force $f(r) \hat{r}$.
- We will see how to obtain a complete solution of the central force problem by employing conservation laws.
- Finally we will apply these concepts to understand planetary motion.

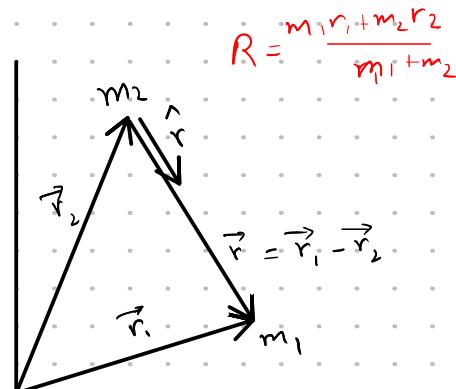
• Central force motion as one body problem

- Two body problem: where two particles are involved with or without interaction.
- Two body problem is difficult to solve, because the system will involve many eq's.
- So we will do some awesome trick to convert the two body problem to a one body problem.
- Let us consider, an isolated system consisting of two particles interacting under central force $f(r)$.
- Masses of the particles m_1 and m_2 and position vectors $\vec{r}_1$ and $\vec{r}_2$ respectively.
- So, we have,

$$\vec{r} = \vec{r}_1 - \vec{r}_2$$

magnitude,

$$r = |\vec{r}|$$
$$= |\vec{r}_1 - \vec{r}_2|$$



- The equations of motion for both the particles are,

$$m_1 \ddot{\vec{r}}_1 = f(r) \hat{r} \quad \text{--- (1)}$$

$$m_2 \ddot{\vec{r}}_2 = -f(r) \hat{r} \quad \text{--- (2)}$$

$$\ddot{\vec{r}} = \frac{d^2 \vec{r}}{dt^2} = \vec{a}$$

and,

attractive, $f(r) < 0$

repulsive $f(r) > 0$

- Now, solving the two equations will solve the whole system. So it is easy. Sst it?

- No. Eqⁿ (1) and (2) are coupled together by $\vec{r} = \vec{r}_1 - \vec{r}_2$. So both the eqⁿs needed to be solved simultaneously. This makes things difficult.

- But, there is an easy way. Replace $\vec{r}_1$ and $\vec{r}_2$ by $\vec{r}$ and center of mass vector $\vec{R} = (m_1 \vec{r}_1 + m_2 \vec{r}_2) / (m_1 + m_2)$. In this case, we will again have two eqⁿs, but the eqⁿ of motion for $\vec{R}$ is trivial as there are no external forces.

- Eqⁿ for $\vec{r}$ is simple, looks like that of a single particle.

- So now, let's check the eqⁿ for $\vec{R}$ first.

No ext. force, so,

$$\ddot{\vec{R}} = 0$$

Solution is, $\vec{R} = \vec{R}_0 + \vec{V}t$

- $\vec{R}_0$ and $\vec{V}$ are constants and they depend upon, the choice of coordinate system and initial condⁿ.

- If the origin is at center of mass, then, $\vec{R}_0 = 0$, $\vec{V} = 0$.

- Now, the eqⁿ for $\vec{r}$. Divide eqⁿ (1) by m_1

$$\ddot{\vec{r}}_1 = \frac{1}{m_1} f(r) \hat{r}$$

Divide eqⁿ (2) by m_2 ,

$$\vec{r}_2 = -\frac{1}{m_2} f(r) \hat{r}.$$

Now subtract,

$$\vec{r}_1 - \vec{r}_2 = \left(\frac{1}{m_1} + \frac{1}{m_2} \right) f(r) \hat{r}$$

$$\Rightarrow \vec{r}_1 - \vec{r}_2 = \left(\frac{m_1 + m_2}{m_1 m_2} \right) f(r) \hat{r}$$

$$\Rightarrow \underbrace{\left(\frac{m_1 m_2}{m_1 + m_2} \right)}_{\mu} \underbrace{(\vec{r}_1 - \vec{r}_2)}_{\vec{r}} = f(r) \hat{r}$$

(μ = reduced mass)

$$\Rightarrow \boxed{\mu \vec{r} = f(r) \hat{r}} \quad \text{--- (3)}$$

↳ So this eqⁿ is identical to a one particle eqⁿ under force $f(r)$ and mass μ .

— So we have reduced our two body problem to a one body problem.

— The problem now is to find $\vec{R}$ as a function of time from eqⁿ (3). Once we know $\vec{R}$, we can find $\vec{r}_1$ and $\vec{r}_2$

$$\text{from } \vec{r} = \vec{r}_1 - \vec{r}_2 \quad \text{--- (i)}$$

$$\text{and } \vec{R} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2}{m_1 + m_2} \quad \text{--- (ii)}$$

$$\mu \ddot{\vec{r}} = f(r) \hat{r}$$

$$\vec{R} = 0$$

Solving for $\vec{r}_1$ and $\vec{r}_2$ gives,

$$\vec{r}_1 = \vec{R} + \left(\frac{m_2}{m_1 + m_2} \right) \vec{r}$$

$$\vec{r}_2 = \vec{R} - \left(\frac{m_1}{m_1 + m_2} \right) \vec{r}$$

$$f(r) = \frac{k}{r^2}$$

— Therefore, given the force function $f(r)$, we can fully solve the problem of central force.

• General properties of central force motion:

- $m\ddot{\vec{r}} = f(r)\hat{r}$ is a vector eqⁿ. Three eq^{ns} to solve.
- But we can use conservation laws to find some general properties of the solⁿ. This will lead us to a eqⁿ with only one scalar variable.

① The motion is confined to a plane.

$$\tau^0 = \frac{dL}{dt} = 0 \quad L = c$$

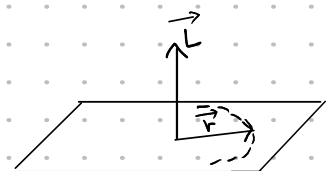
- central force $f(r)\hat{r}$ is in radial direction only. Hence it can exert no **torque** on m .
- So the angular momentum $\vec{L}$ of m is constant.
- This means: the motion is confined to a plane.

$$\begin{aligned} \vec{L} &= \vec{r} \times \vec{p} & L &= r p \sin\theta \\ &= \vec{r} \times m\vec{v} & , \quad v &= \frac{dr}{dt} = \dot{r} \end{aligned}$$

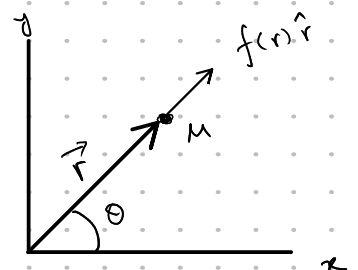
So $\vec{r}$ is perpendicular to $\vec{L}$.

And $\vec{L}$ is fixed (constant). So $\vec{r}$ can only move in a plane perpendicular to $\vec{L}$.

- Since the motion is confined in a plane we can choose our coordinates, so that the motion is in xy plane. In polar coordinates: $m\ddot{\vec{r}} = f(r)\hat{r}$ becomes,



$$\begin{aligned} (r, \theta) \quad m(\ddot{r} - r\dot{\theta}^2) &= f(r) & \text{--- ④} \\ m(r\ddot{\theta} + 2\dot{r}\dot{\theta}) &= 0 & \text{--- ⑤} \end{aligned}$$



② Energy and angular momentum are constants of motion.

- We have reduced the problem to two dimensions by using the fact the the direction of $\vec{L}$ is constant.
- Other two important constants $\rightarrow$ magnitude of angular momentum $l \equiv |\vec{L}|$ and Energy E .

- Using these two constants make central force motion very insightful.

Magnitude of angular momentum

$$l = m r v_{\theta} = m r^2 \dot{\theta} \Rightarrow \dot{\theta}^2 = \frac{l^2}{m^2 r^4}$$

$$\underline{f(r)} \cdot \underline{U}$$

Energy,

$$E = \frac{1}{2} m v^2 + U(r) \\ = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) + U(r)$$

$$\text{Where, } U(r) = \int_{r_a}^r f(r) dr, \quad U(r_a) = 0$$

is the potential energy.

- Check the energy eqⁿ,

$$\ddot{r} = \frac{f(r)}{m}$$

$$E = \frac{1}{2} m \dot{r}^2 + \frac{1}{2} m r^2 \dot{\theta}^2 + U(r)$$

$$E = \frac{1}{2} m \dot{r}^2 + \frac{1}{2} \frac{l^2}{m r^2} + U(r)$$

This looks like eqⁿ of motion of a particle in one dimension. All reference to θ is gone.

Now,

$$E = \frac{1}{2} m \dot{r}^2 + U_{\text{eff}} \quad \text{--- (6)}$$

$$\underline{r} \times (\underline{r} \times \underline{r})$$

— Where $U_{\text{eff}} = \frac{1}{2} \frac{l^2}{m r^2} + U(r)$ is the effective potential.

- The extra term in potential is the centrifugal potential.

- Now a formal solution of (6).

$$E = \frac{1}{2} m \dot{r}^2 + \frac{1}{2} \frac{l^2}{m r^2} + U(r)$$

$$\Rightarrow \frac{dr}{dt} = \left\{ \frac{2}{m} (E - U_{\text{eff}}) \right\}^{1/2} \quad \text{--- (7)}$$

$$\Rightarrow t - t_0 = \int_{t_0}^t dt = \int_{r_0}^r \frac{dr}{\left\{ \frac{2}{m} (E - U_{\text{eff}}) \right\}^{1/2}}$$

$$\text{--- (7)}$$

$$t = g(r)$$

- Eqⁿ (7) gives r as a function of t .

- We can also find θ as a function of t .

$$\begin{aligned} \textcircled{b} \quad \frac{d\theta}{dt} &= \frac{l}{mr^2} \quad \text{--- (b)} \\ \textcircled{a} \quad \frac{dr}{dt} &= -\frac{d\theta}{dr} \end{aligned}$$
$$\Rightarrow \theta - \theta_0 = \int_{t_0}^t \frac{l}{mr^2} dt \quad \left(\begin{array}{l} \text{because } r \text{ is known} \\ \text{as a function of } t \end{array} \right)$$

- So we have got $r(t)$ and $\theta(t)$. We can also obtain $r(\theta)$, the orbit of the particle. Dividing (b) by (a),

$$\frac{d\theta}{dr} = \frac{l}{mr^2} \times \frac{1}{\left\{ \frac{2}{m} (E - U_{\text{eff}}) \right\}^{1/2}}$$

- This completes the formal solution of central force problem. We can obtain $r(t)$, $\theta(t)$ and $r(\theta)$ once we get a potential $U(r)$.

