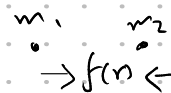


## Lecture 10: Central force and planetary motion



### Energy eq<sup>n</sup> and energy diagram

- We found two equivalent ways of writing  $E$  in the Center of mass system.

$$E = \frac{1}{2} \mu v^2 + U(r) \quad \text{--- (1)}$$

and,

$$E = \frac{1}{2} \mu \dot{r}^2 + U_{\text{eff}}(r) \quad \text{--- (2)}$$

- Eq<sup>n</sup> (1) is handy for evaluating  $E$ .
- Eq<sup>n</sup> (2) depends on single coordinate  $r$ . Good to solve. Because  $\theta$  is suppressed. AS

$$\frac{1}{2} \mu (r\dot{\theta})^2 = \frac{l^2}{2\mu r^2}$$

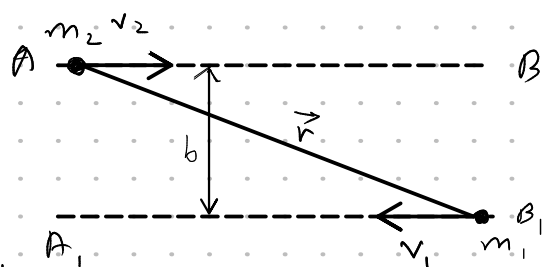
$$\text{and } U_{\text{eff}}(r) = \frac{l^2}{2\mu r^2} + U(r)$$

- Example: Two non-interacting particles  $m_1$  and  $m_2$  move towards each other with velocity  $\vec{v}_1$  and  $\vec{v}_2$ . Their paths are offset by a distance  $b$ .

- Non-interacting, so  $f(r) = 0$

- Relative velocity,

$$\begin{aligned} \vec{V}_0 = \vec{v} &= \vec{r}_1 - \vec{r}_2 \\ &= \vec{v}_1 - \vec{v}_2 = \text{constant.} \end{aligned}$$



- Total energy,

$$(1) \Rightarrow E = \frac{1}{2} \mu v_0^2 + U(r) = \frac{1}{2} \mu v_0^2$$

- Effective potential,

$$U_{\text{eff}} = \frac{l^2}{2\mu r^2} + U(r) = \frac{l^2}{2\mu r^2}$$

$$U_{\text{eff}} = \frac{l^2}{2\mu r^2} + \textcircled{U(r)}$$

$$\text{- Hence } (2) \Rightarrow E = \frac{1}{2} \mu \dot{r}^2 + \frac{l^2}{2\mu r^2} = \frac{1}{2} \mu v_0^2$$

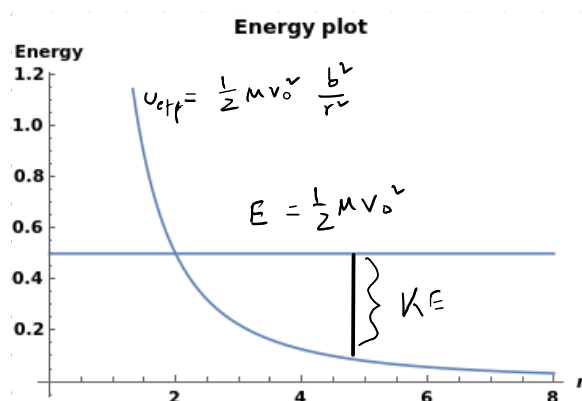
$$\textcircled{1} = \textcircled{2}$$

- When  $m_1$  and  $m_2$  pass each other,  $r = b$  and  $\dot{r} = 0$ .

$$\text{So, } E = \frac{L^2}{2\mu b^2} = \frac{1}{2} \mu v_0^2$$

$$\Rightarrow \boxed{L = \mu b v_0}$$

and,  $U_{\text{eff}}(r) = \frac{1}{2} \mu v_0^2 \frac{b^2}{r^2}$



- Kinetic energy associated with radial motion  $\rightarrow$

$$K = \frac{1}{2} \mu \dot{r}^2 = E - U_{\text{eff}}$$

$$U_g \propto \frac{1}{r^2}$$

$$(r = b)$$

- KE is never negative. So motion is restricted to the region where,  $E - U_{\text{eff}} \geq 0$ .

- Initially  $r$  is very large. As the particles approach, the KE decreases vanishing at turning point ( $\dot{r} = 0$ ),  $r_t$ . Here the motion is purely tangential.

- At the turning point,  $E = U_{\text{eff}}(r_t)$

$$\frac{1}{2} \mu v_0^2 = \frac{1}{2} \mu v_0^2 \frac{b^2}{r_t^2} \Rightarrow r_t = b.$$

### • Planetary motion :

- Motion of earth around the sun. Or motion of Satellites around earth.

- In this case,  $f(r) \neq 0$ .

$$f(r) = - \frac{G m_1 m_2}{r^2}$$

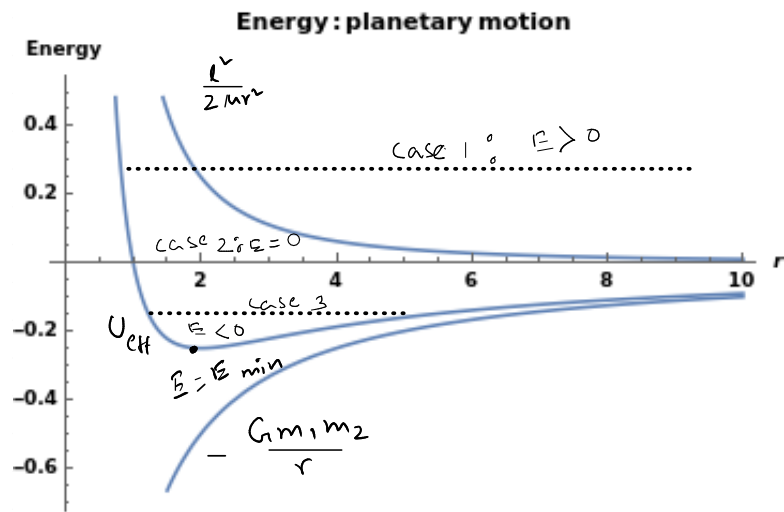
$$U(r) = - \frac{G m_1 m_2}{r}$$

$$U_{\text{eff}} = \frac{L^2}{2\mu r^2} + U(r)$$

- So the effective potential,  $U_{\text{eff}} = - \frac{G m_1 m_2}{r} + \frac{L^2}{2\mu r^2}$

- If  $l \neq 0$ , repulsive centrifugal potential  $\frac{l^2}{2mr^2}$  dominates at small  $r$ .

- The plot shows various values of total energy,
- $K E = E - U_{\text{eff}}$ , motion is restricted to the region where,  $K E \geq 0$ .



- The nature of motion is determined by total energy  $E$ .

→ • Case ① :  $E > 0$

—  $r$  is unbounded for large values. Must exceed a certain minimum if  $l \neq 0$ . particles are kept apart by "centrifugal barrier".

— Hyperbolic orbits.

• Case ② :  $E = 0$

— Similar to case ①. Boundary between bounded and unbounded motion.

— Parabolic orbit.

• Case ③ :  $E < 0$

— The motion is bounded for both small and large  $r$ . Bound system.

— Elliptical orbit.

• Case ④ :  $E = E_{\text{min}}$

—  $r$  is restricted to 1 value. Particles stay at a constant distance.

— circular orbit.

## • Solving planetary motion

- We have the potential

$$U(r) = -G \frac{Mm}{r} = -\frac{c}{r}$$

$M \rightarrow$  Mass of Sun/planet

$m \rightarrow$  Mass of planet/satellite

$$M = \sum m$$

$$m = \sum m$$

$$c = G M m$$

- We have from previous lecture,

$$\frac{d\theta}{dr} = \frac{l}{mr^2} \times \frac{1}{\{(2/m)(E - U_{eff})\}^{1/2}}$$

$$\dot{r} = ( )$$

$$\dot{\theta} = ( )$$

$$\frac{d\theta}{dr} = ( )$$

$$\Rightarrow \theta - \theta_0 = \int_{\theta_0}^{\theta} d\theta = l \int \frac{dr}{r(2MEr^2 + 2Mc r - l^2)^{1/2}} \quad \text{--- (a)}$$

here  $\theta_0 \rightarrow$  constant of integration.

- The integral in (a) can be obtained from integration table.

The result is,

$$\theta - \theta_0 = \text{ArcSin} \left[ \frac{Mc r - l^2}{r(l^2 c^2 + 2ME l^2)^{1/2}} \right]$$

$$\Rightarrow Mc r - l^2 = r(l^2 c^2 + 2ME l^2)^{1/2} \sin(\theta - \theta_0)$$

Now solving for  $r$ ,

$$\Rightarrow r = \frac{(l^2/Mc)}{1 - (1 + (2El^2/Mc^2))^{1/2} \sin(\theta - \theta_0)}$$

Here,  $\theta_0$  is usually taken as  $\pi/2$

- For further simplification, we define two parameters

$$r_0 \equiv \frac{l^2}{\mu c} \quad (r_0 \text{ is the radius of the circular orbit for corresponding } l, \mu, c)$$

$$e \equiv \sqrt{1 + \frac{2El^2}{\mu c^2}} \quad (e \text{ is the eccentricity, characterizes the shape of the orbit.})$$

- Use these two parameters in the previous eq<sup>n</sup>, it becomes,

$$r = \frac{r_0}{1 - e \cos \theta}$$

$x, y$

- This eq<sup>n</sup> looks more familiar in Cartesian coordinates.  $(x, y)$ .

$$\begin{array}{l|l} x = r \cos \theta & r = \sqrt{x^2 + y^2} \\ y = r \sin \theta & \end{array}$$

$$\text{So, } r = \frac{r_0}{1 - e \cos \theta}$$

$$\Rightarrow r - e r \cos \theta = r_0$$

$$\Rightarrow \sqrt{x^2 + y^2} - e x = r_0$$

$$\Rightarrow x^2 + y^2 = (r_0 + e x)^2$$

$$\Rightarrow x^2 + y^2 = r_0^2 + e^2 x^2 + 2e r_0 x$$

$$\Rightarrow (1 - e^2) x^2 + y^2 - 2e r_0 x = r_0^2$$

This is the eq<sup>n</sup> of orbits for planetary motion. (General)

• Now different cases -

$$(1 - \epsilon^2)x^2 - 2r_0\epsilon x + y^2 = r_0^2$$

• Case ①,  $\epsilon > 1$  : ( $E > 0$ )

- Coefficients of  $x^2$  and  $y^2$  are unequal and opposite in sign.
- So it will have this form,  $y^2 - Ax^2 - Bx = \text{const.}$
- This is the eq<sup>n</sup> of a hyperbola.

• Case ②,  $\epsilon = 1$  : ( $E = 0$ )

- Eq<sup>n</sup> becomes,

$$x = \frac{y^2}{2r_0} - \frac{r_0}{2}$$

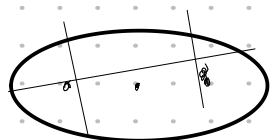
- This is the eq<sup>n</sup> of a parabola.

• Case ③,  $0 \leq \epsilon < 1$  : ( $-\frac{mc^2}{2k^2} \leq E < 0$ )

- Coefficients of  $x^2$  and  $y^2$  are unequal, but has the same sign.

- Eq<sup>n</sup> :  $y^2 + Ax^2 - Bx = \text{const.}$

- Eq<sup>n</sup> of an ellipse. (geometric center not at the origin of coord. system).



• Case ④,  $\epsilon = 0$  : ( $E = -\frac{mc^2}{2k^2}$ )

- Eq<sup>n</sup> becomes,  $x^2 + y^2 = r_0^2$

- Circular orbit.

- (special case of ellipse)

## • Elliptical orbits

- Elliptical orbits are very important. ( $E < 0$ ,  $0 \leq e < 1$ )

- The orbit eq<sup>n</sup> is,

$$r = \frac{r_0}{1 - e \cos \theta}$$

$$1 + e$$

- maximum value of  $r$  occurs at  $\theta = 0$ ,

$$r_{\max} = \frac{r_0}{1 - e}$$

- minimal value of  $r$  occurs at  $\theta = \pi$ ,

$$r_{\min} = \frac{r_0}{1 + e}$$

- length of the major axis,

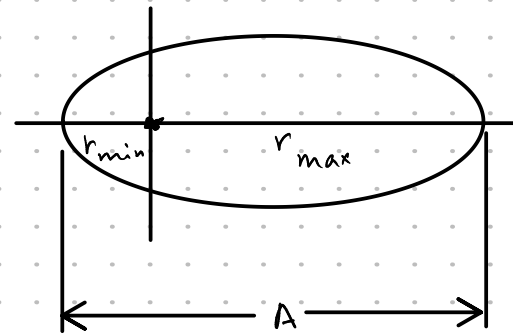
$$\begin{aligned} A &= r_{\min} + r_{\max} \\ &= r_0 \left( \frac{1}{1+e} + \frac{1}{1-e} \right) \end{aligned}$$

$$\Rightarrow A = \frac{2r_0}{1 - e^2}$$

$$\text{Now, } r_0 = \frac{l^2}{mc^2}, \quad e = \sqrt{1 + \frac{2El^2}{mc^2}}$$

$$\Rightarrow A = \frac{2l^2/mc^2}{1 - \left(1 + \frac{2El^2}{mc^2}\right)}$$

$$\Rightarrow A = \frac{c}{-E}$$



- This means shape of the major axis is independent of  $l$ . Orbits with the same major axis has the same energy.

— The ratio of  $r_{\max}$  and  $r_{\min}$ ,

$$\frac{r_{\max}}{r_{\min}} = \frac{r_0/(1-\epsilon)}{r_0/(1+\epsilon)} = \frac{1+\epsilon}{1-\epsilon}$$

— When,  $\epsilon \rightarrow 0$ ,  $r_{\max}/r_{\min} \approx 1$ . So the ellipse becomes a circle.

— When  $\epsilon \rightarrow 1$ , the ellipse become elongated.

- All the planets in solar system are in elliptical orbit.

### • Kepler's laws :

- Johannes Kepler was an assistant of Tycho Brahe.
- Tycho Brahe recorded data for orbits of planets using telescope.
- Kepler took this data and formulated the laws.
- The laws are :

- ① Each planet moves in an ellipse with the sun at its focus.
- ② The radius vector from the sun to a planet sweeps out equal area in equal times.
- ③ The period of revolution  $T$  of a planet about the sun is related to the major axis of ellipse  $A$  by

$$T^2 = K A^3$$

Where  $K$  is same for all planets.

— We already saw 1st law in the previous section.

## • Proof of 3rd law:

In planetary motion,  $U(r) = -\frac{C}{r}$

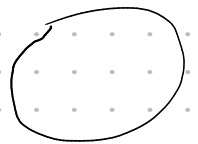
and we have,

$$E = \frac{1}{2} m \dot{r}^2 + U_{\text{eff}}$$

$$\Rightarrow \frac{dr}{dt} = \sqrt{\frac{2}{m} (E - U_{\text{eff}})}$$

$$\Rightarrow t_b - t_a = \int_{r_b}^{r_a} \frac{dr}{\sqrt{\frac{2}{m} (E - U_{\text{eff}})}}$$

$$\Rightarrow t_b - t_a = m \int_{r_a}^{r_b} \frac{r dr}{(2mEr^2 + 2mCr - l^2)^{1/2}}$$



It is a standard integral - Soln is,

$$t_b - t_a = \frac{\sqrt{2mEr^2 + 2mCr - l^2}}{2E} \Big|_{r_a}^{r_b} - \left( \frac{mC}{2E} \right) \frac{1}{\sqrt{-2mE}} \arcsin \left( \frac{-2mEr - mC}{\sqrt{m^2 C^2 + 2mEl^2}} \right) \Big|_{r_a}^{r_b}$$

For a complete period,  $t_b - t_a = T$  and  $r_b = r_a$

So the result,

$$T = \frac{\pi m C}{-E} \frac{1}{\sqrt{-2mE}}$$

$$\Rightarrow T^2 = \frac{\pi^2 m C^2}{(-2E^3)}$$

$$\Rightarrow T^2 = \left( \frac{\pi^2 m}{2C} \right) A^3$$

(using  $A = -\frac{C}{E}$ )

$$\Rightarrow T^2 = K A^3$$

The first term in rhs vanishes.  
The second term - arcsin changes by  $2\pi$